# Source ROS2

source /opt/ros/humble/setup.bash

# Kill any existing processes

pkill -f gazebo

pkill -f gz

pkill -f prompt

pkill -f ros2

# Start all components

gz sim phase3\_ifc\_digital\_twin.sdf &

sleep 10

python3 phase3\_prompt\_orchestrator\_executor.py &

sleep 3

python3 enhanced\_workflow\_simulator.py &

# Keep terminal alive

echo "System running. Press Ctrl+C to stop all processes"

wait